

Exercise sheet 4

Solutions

Exercise 1. i) The noise \mathbf{u}_k has distribution $N(\cdot; 0, U_k + \tilde{U}_k)$

ii) Using the result from the lecture notes in the case of a one-dimensional state, we have

$$M_k = \frac{\sqrt{\tilde{P}_k}}{\sqrt{P_k}} = \frac{\sqrt{P_k + \tilde{U}_k}}{\sqrt{P_k}} = \sqrt{1 + \tilde{U}_k/P_k}$$

so that

$$\begin{aligned}\check{F}_k &= M_k F_k = M_k = \sqrt{1 + \tilde{U}_k/P_k} \\ c_k &= \check{m}_k - M_k F_k \hat{m}_{k-1} = (1 - \check{F}_k) \hat{m}_{k-1} \\ \check{U}_k &= M_k U_k M_k^T = (1 + \tilde{U}_k/P_k) U_k,\end{aligned}$$

as required.

The intervention which consists of adding an independent noise term (resulting in the total covariance of the transition noise being $U_k + \tilde{U}_k$) cannot be used if the desired predicted variance is “smaller” than the original predicted variance P_k . Indeed, $P_k + \tilde{U}_k < P_k$ cannot hold since \tilde{U}_k is a variance and is therefore positive definite. In this sense, the change-of-moments intervention is more general. In the context of a first-order polynomial trend model, this situation corresponds to $M_k < 1$ and, thus, $\check{F}_k < 1$, c_k is of the same sign as \hat{m}_{k-1} and $\check{U}_k < U_k$.

Exercise 2. i) The posterior distribution is characterised by

$$\begin{aligned}p_{\boldsymbol{\theta}_{1:K} | \mathbf{y}_{1:n}}(\boldsymbol{\theta}_{1:K} | \mathbf{y}_{1:n}) &\propto p_{\mathbf{y}_{1:n} | \boldsymbol{\theta}_{1:K}}(\mathbf{y}_{1:n} | \boldsymbol{\theta}_{1:K}) p_{\boldsymbol{\theta}_{1:K}}(\boldsymbol{\theta}_{1:K}) \\ &\propto \prod_{k=1}^K \theta_k^{m_k} \prod_{k=1}^K \theta_k^{\alpha_k - 1} \\ &\propto \prod_{k=1}^K \theta_k^{m_k + \alpha_k - 1}\end{aligned}$$

ii) The marginal likelihood is

$$\begin{aligned}p_{\mathbf{y}_{1:n}}(\mathbf{y}_{1:n}) &= \int p_{\mathbf{y}_{1:n} | \boldsymbol{\theta}_{1:K}}(\mathbf{y}_{1:n} | \boldsymbol{\theta}_{1:K}) p_{\boldsymbol{\theta}_{1:K}}(\boldsymbol{\theta}_{1:K}) d\theta_1 \dots d\theta_K \\ &= \frac{\Gamma(\sum_{i=1}^K \alpha_i)}{\prod_{k=1}^K \Gamma(\alpha_k)} \int \prod_{k=1}^K \theta_k^{m_k + \alpha_k - 1} d\theta_1 \dots d\theta_K = \frac{\Gamma(\sum_{i=1}^K \alpha_i)}{\Gamma(n + \sum_{k=1}^K \alpha_k)} \prod_{k=1}^K \frac{\Gamma(\alpha_k + m_k)}{\Gamma(\alpha_k)}\end{aligned}$$

iii) The marginal likelihood corresponding to a uniform prior is

$$p'_{\mathbf{y}_{1:n}}(\mathbf{y}_{1:n}) = \frac{\Gamma(K)}{\Gamma(n + K)} \prod_{k=1}^K \frac{\Gamma(m_k + 1)}{\Gamma(1)}$$

so that the corresponding Bayes factor over all time steps is

$$B_{n,n} = \frac{p_{\mathbf{y}_{1:n}}(\mathbf{y}_{1:n})}{p'_{\mathbf{y}_{1:n}}(\mathbf{y}_{1:n})} = \frac{\Gamma(\sum_{i=1}^K \alpha_i) \Gamma(n + K)}{\Gamma(n + \sum_{k=1}^K \alpha_k) \Gamma(K)} \prod_{k=1}^K \frac{\Gamma(\alpha_k + m_k) \Gamma(1)}{\Gamma(\alpha_k) \Gamma(m_k + 1)}.$$